

Instantiating the Knowledge Plane

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Abstract

In 2003, Clark et al. proposed the “Knowledge Plane”, a layer of intelligent agents that share rich information about network state in order to collaboratively manage the Internet across administrative boundaries. The technology of the day lacked the two capabilities it demanded most: *reasoning* and *unstructured communication*. Thus, automated network management has remained largely confined to single domains, while inter-domain problems are still resolved by human operators on the phone. We argue that agentic large language models can finally unlock the potential of the Knowledge Plane, but that doing so will require solving new research problems that arise particularly in this decentralized, multi-agent, cooperative setting that have received limited attention in the literature thus far.

CCS Concepts

• **Networks** → **Network management**; • **Computing methodologies** → **Multi-agent systems**.

Keywords

Knowledge Plane, Multi-Agent Systems, Interdomain Routing

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1 Introduction

The Internet is designed to be general, composable, and decentralized – properties that enable it to scale globally. However, *managing* components of the Internet can be a formidable task precisely because of its decentralized nature and complexity – so much so that entire subfields have been devoted to network configuration, routing, troubleshooting, defense,

load balancing, and more [8, 10, 31, 44, 54]. These challenges currently require a great deal of human coordination on top of the sophisticated algorithms, software, and hardware built to solve these problems.

In the face of so much complexity and manual intervention, one would naturally ask: what can we hope to automate away? Over decades of effort, researchers have proposed numerous solutions to automate the configuration and verification of pieces of network management [9, 26, 27, 29, 41, 65, 75]. Yet protocols for rich *interdomain* communication are limited, and difficult to upgrade and adapt for unforeseen applications – so automated network debugging and decision-making tends to be limited to *single-domain* solutions.

Presciently, in 2003, Clark et al. proposed a solution: a “Knowledge Plane” run by intelligent agents that share rich information about network state with the goal of collaborative network management, including troubleshooting, routing, configuration, intrusion detection and more [20]. The paper envisioned a user bringing a question like, “Why can’t I load this webpage?” to an agent which might in turn collect data about routes and DNS from its local network, and ask agents from remote networks about the location of their firewalls or their provisioned server capacities. In the pre-LLM era, however, it was not clear *how* one would implement a Knowledge Plane. Although several lines of subsequent work have attempted to instantiate a Knowledge Plane [3, 16, 28, 52, 60, 83], the state of the art technology at the time lacked sufficient *unstructured communication* and *reasoning* capability to autonomously and collaboratively diagnose and solve interdomain network problems. It is only now that we have models – agentic large language models – powerful enough to truly instantiate a Knowledge Plane.

The natural instinct of the skeptical systems researcher may be to push back against the idea of unleashing unpredictable agents on the Internet, or perhaps to question the technical value of an agentic layer over the Internet. We acknowledge these concerns, yet hope to argue that LLM agents can fill a real technical need that current Internet protocols and automated troubleshooting solutions do not adequately solve, while also outlining concrete challenges – particularly in safety and security – that must be met in order for deployment to be possible. In short, we ask the reader to temporarily ignore the question of whether we *should* manage the Internet with



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agents, and join us for the thought experiment of what benefits and challenges we might uncover if we were to do so.

Promise: Decentralized, online, adaptive decision making. Many real problems require communication across network domains to troubleshoot. To name a few examples, diagnosing protocol failures due to unforeseen middlebox behavior [49, 64], diagnosing path inflation [71], identifying and root-causing interdomain congestion [25], and identifying unreachable “black holes” [40] are all examples of distributed network failures that cannot be easily diagnosed nor resolved with the information available in a single autonomous system.

Cooperating LLM agents hosted by every network, following the Knowledge Plane’s blueprint, bring two main benefits: decentralized collaboration and adaptive communication.

First, LLMs can *collaborate* to solve complex troubleshooting tasks or make decisions involving multiple stakeholders. Today, such problems would require multiple human operators to coordinate, requiring potentially several communication rounds and hours of human effort to debug. Importantly, even though some automated tools can be used to inspect logs or perform data analysis and speed up this process to a degree, *interdomain* network management is difficult because no individual operator has access to all of the data, infrastructure, and configurations that a route or packet is going to touch as it crosses the Internet.

Second, LLMs can *adapt* their communication as needed by the application at hand: natural language functions as a flexible and completely forward- and backward-compatible protocol. Fixed protocols to exchange telemetry between ASes (e.g. netflow data, routing configuration) between operators might be helpful, but they ultimately constrain the data that is shared: new protocols or systems might not be able to be encoded in the inter-AS telemetry format as one AS adopts a new technology and another lags behind. An agentic model brings the ability of a sender to *explain* what new data represents, even as new technologies are adopted. Furthermore, operators may have privacy concerns and hence not *want* to share arbitrary telemetry data unless the data is explicitly necessary to solve a problem at hand. Deciding which data to share requires reasoning, something that LLMs might resolve but a static protocol with traditional ACLs cannot.

In §3, we present a series of simulated case studies where agents at different organizational domains collaborate to debug availability failures, defend against security risks, and optimize financial goals. This illustrates the capacity of today’s agents to communicate, collaborate, and resolve the kinds of interdomain issues that today force human network operators to be available on the phone around-the-clock.

Challenge: Collaboration without trust. In §4, we explore why an agentic Knowledge Plane is not (yet?) a good idea. Some open challenges are shared with many other systems

that hope to adopt LLM technology for better management, especially challenges in scalability [18, 37, 45, 46, 62, 70, 74] and LLM correctness and robustness to attacks [6, 11, 32, 34, 39, 47, 66, 72, 87].

At the same time, we think an agentic Internet brings challenges that are uncommon to the broader research world, as we expect agents to *collaborate* towards a shared goal (global routing) despite a lack of *trust* between collaborating agents as well as potentially conflicting *local* goals from diverse edge applications. This plays out in two open questions we see: data privacy (operators do not generally share all of their routing preferences, and yet agents may need to share some of this information to diagnose issues) and strategic behavior (untrusted networks may selectively withhold information or even lie). As we will discuss further in §4, these kinds of challenges are less well-explored in either the ML literature or the literature of applying ML to computer systems. Hence, an agentic Internet brings new research perspectives into AI safety and multiagent coordination.

2 Background and Related Work

In this section, we present the original vision of the Knowledge Plane (KP) as envisioned by Clark et al. [20], review significant literature that has made strides towards realizing that vision since 2003, highlight the remaining gaps to realizing that full vision, and outline concrete requirements that our agentic architecture should satisfy in order to realize the interdomain vision of the Knowledge Plane.

2.1 The Knowledge Plane Vision

The goal of the Knowledge Plane was to create “a fundamentally different sort of network that can assemble itself given high level instructions, reassemble itself as requirements change, automatically discover when something goes wrong, and automatically fix a detected problem or explain why it cannot do so” [20]. In the paper, the authors argue that a “cognitive system” is necessary to bring *reasoning* into the management of Internet infrastructure (despite the limitations of AI reasoning systems at the time). At the heart of the paper is an example – which we replicate in §3 – in which a user asks a broad and high level question (“Why can’t I access acm.org?”) and a distributed collection of agents from the user’s AS, the ACM’s AS, and even agents at individual servers exchange information about routes, DNS availability, firewalls, server capacity, etc.

Today, debugging an outage with this level of data availability would require phone calls between operators. However, the phone-call approach is only feasible for major CDNs, networks, and datacenter operators to use in only the worst-case of outages – and hence most individual problems of this nature are never resolved at all. Hence, the KP approach represented

then, and still represents today, a major advance in the ability to diagnose and potentially repair interdomain challenges.

2.2 Then and Now

Some have attempted to explicitly instantiate a Knowledge Plane [3, 16, 28, 52, 60, 83], but prior to LLMs, the required capabilities for reasoning and unstructured communication were not available and hence these approaches lacked the “cognitive” depth envisioned by Clark et al.

Other lines of work in the intra-domain setting have pushed the reasoning aspects of a Knowledge Plane approach further. For example, work on *self-driving networks* [2, 28, 33, 43, 68, 69, 73, 77] and related work on machine learning for network management applications, particularly reinforcement learning [55–57], are particularly rich. The seminal paper on self-driving networks [28] outlined a number of goals of network automation, covering data collection, in-network analytics and decision making, security, scalability, learning, and dynamic decision making. We see many of these contributions as *supportive* of the proposal of an agentic Knowledge Plane: these works illustrate a division of labor in which agents can reason and communicate, but the job of data collection and analytics are still best left to the programmable data plane and traditional statistics, which agents can access as tools.

Significant progress has been made towards leveraging LLMs in the context of network management. One line of work proposes *intent-based networking* [4, 21, 35, 36, 59, 65, 75, 81, 81] in which network operators should be able to express *goals and outcomes* (in some interface such as, but not limited to, natural language) and the network should translate and accomplish that intent – but the goal is typically to translate user intent into network behavior; network devices cannot necessarily send unstructured expressions to each other. Agentic techniques have already begun to be incorporated into network and software system troubleshooting [5, 14, 67, 76, 78–82, 86, 88].

Altogether, the Knowledge Plane vision is far more feasible today than it was in 2003, in part due to advances in LLM technology, but also due to advances in the network management literature as described above.

2.3 Requirements for a Knowledge Plane

We now consider the core properties that a Knowledge Plane requires and what remains unsolved for the interdomain Knowledge Plane vision to be realized. From Clark et al. [20], we derive the following list of requirements:

- R1 Abstract high-level goals from low-level actions.**
- R2 Learn from past actions.**
- R3 Operate effectively in the face of generality.**

R4 Extend its perspective to the entire global network by merging perspectives and activities between different networks.

R5 Function in the presence of incomplete, inconsistent, misleading, or malicious information.

R6 Perform appropriately in the presence of conflicting or inconsistent higher-level goals among the Internet’s different stakeholders.

Among these requirements, we observe that R1-R3 largely test *single-agent* capabilities that can be explored within a single domain. *The existing literature on AI-based network management largely solves all of them!* Taking one recent and prominent work as an example, Meta’s recent paper [81] demonstrates a *production* tool that moves between low level data formats and higher level human abstractions (R1), learns and models anomalies (R2), and adapts as new tools and technologies are deployed (R3).

On the other hand, the remaining R4-R6 test *multi-agent* interactions, which is required for multi-domain settings. These capabilities have not yet been demonstrated in the literature.

To explore this possibility, in the following section, we select three case studies chosen to illustrate that today’s LLMs are capable of at least some of the reasoning and communication requirements detailed in R4-R6, pointing the way towards the possibility of an interdomain Knowledge Plane.

3 Case Studies

In this section, we walk through a series of case studies to better understand whether agents would meet the three criteria we chose to study in §2. We first (§3.2) simulate an example from the KP paper [20], testing the agents’ ability to reason about a global perspective (R4). We then (§3.3) illustrate a scenario in which the LLMs demonstrate capabilities to consider conflicting and even malicious information (R5 and R6). Finally, we consider a more dynamic setting in which agents can perform unconstrained load balancing (§3.4).

3.1 Experimental Setup

We use Mininet [50] to build a virtualized network of hosts, each equipped with an agent acting as a system administrator. Agents treat the emulated network as a real one, issuing real commands on their respective hosts in the Mininet environment. Experiments run in simulated time, so scenarios spanning days of network activity complete in minutes.

Each agent has full administrative control over its own host, and is informed of its immediate neighbors, but has no global view of the network. Each agent receives a prompt that briefly describes its organization’s objectives and policies. We keep these prompts minimal: enough to act on the organization’s behalf, but without details of the experimental scenario. In particular, agents are never told which fault was

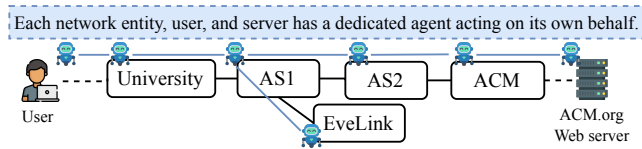


Figure 1: Simulated network for fault diagnosis wherein a student tries to access `www.acm.org`.

injected, or that one was injected in the first place. Agents communicate outside the data plane, over a separate dedicated message channel (the Knowledge Plane), which they use to send messages to their immediate neighbors.

Each agent is provided with the same set of tools: `exec` to run a shell command on their host, `send_message` to communicate in natural language with other neighboring agents via the Knowledge Plane, `idle` as a no-op. Every tool usage carries a mandatory free-text justification, which is the source of the reasoning quoted throughout this section. An agent that calls `report_t_done` goes dormant rather than terminating: a message from a neighbor wakes it, and it keeps taking turns until it reports again. An experiment ends once every agent is simultaneously dormant, or when a fixed budget of iterations is exhausted.

We ran all experiments with four models: Claude Opus 4.7, GPT 5.5, and smaller open-weight models Qwen 2.5 72B (AWQ) (with vLLM [48]) and two NVIDIA RTX PRO 6000 Blackwell Max-Q) and GLM 5.2 FP4 (via Together AI ¹).

All our code and experimental results, including prompts, logs, and reports, are openly available ².

3.2 Fault Diagnosis

Consider an example proposed by Clark et al. [20], wherein a university student cannot reach `www.acm.org` (fig. 1). The cause may lie anywhere along the path: a firewall block at the university, a routing failure upstream, a breakdown in name resolution, or even a server overload at ACM. Diagnosing it requires *cooperation across networks* with different vantage points but under *separate administrative control*.

We investigate our Knowledge Plane’s ability to recognize and recover from an outage of `www.acm.org` under three different causes. We initialize each agent with the basic rules and responsibilities of its organization. For instance, for AS1:

Prompt: AS1

You belong to the Knowledge Plane, and represent autonomous system AS1. University and EveLink are your customers, and pay you for Internet transit. AS2 is your

peer, and neither one of you pays the other (you exchange traffic as equals). Your goal is to maximize revenue, and provide reliable Internet transit to your customers.

The student always takes the first step by asking their local agent for help. The agent then collaborates with the rest of the Knowledge Plane to finally return a diagnosis.

Cause #1: University firewall. The university administration team mistakenly introduced a firewall rule that inadvertently blocked requests to `www.acm.org`. For all models, the user agent first replicated the reported issue, ran local diagnostics, and *escalated the problem* automatically to the university. The university agent then found the smoking gun, which was later relayed back to the user:

Quote: University

GLM 5.2 FP4

Firewall policy on the University gateway (Uni) is blocking all traffic to 198.82.0.0/24, which includes 198.82.0.1 (acm.org). [...] Per policy, changes to firewall rules require administrator approval — I cannot override them autonomously. Administrators have been notified of this finding and the proposed fix.

Cause #2: AS1’s stale DNS entry. Now, the user’s requests pass freely through the university’s firewall, but AS1 is configured with an out-of-date DNS entry resolving `www.acm.org` to an old ACM IP address. As the user’s machine relies on AS1 to resolve `www.acm.org`, every subsequent HTTP request to that website is forwarded to the wrong location.

Opus, GPT, and GLM quickly escalated the problem up to AS1, which correctly identified the DNS misconfiguration. However, it deemed the required change sensitive enough to require administration approval, notifying the administrators and warning University of the findings, which ultimately relayed to the user:

Quote: User

Claude Opus 4.7

acm.org failed to load because our upstream DNS provider is handing out a wrong address for the site [...]. The issue has already been flagged to that provider’s administrators, so no action is needed from you on that front.

Qwen, on the other hand, gathered the same evidence but read it as a routing issue rather than a DNS one. It was ultimately unable to provide an accurate report to the user.

Cause #3: Overloaded ACM server. In this scenario, neither the university’s firewall nor AS1 are the source of the outage. We instead exhaust the ACM web server’s capacity by having

¹<https://www.together.ai>

²<https://fchamicapereira.github.io/agentic-networks/>

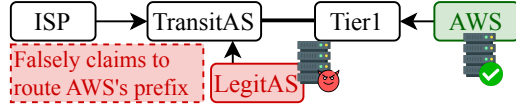


Figure 2: Topology of the Celer Bridge experiment. Arrows denote provider/client relationship, and solid lines peer/peer.

EveLink issue *benign* requests to a blocking HTTP endpoint of the ACM webserver. The server remains reachable, but rejects new connections.

Both Opus and GPT escalated to Web and correctly identified overload as the root cause. Web then shared its findings with ACM, including client information and implementation details. ACM relayed the diagnosis back to the user but, as instructed, withheld the private implementation details and the fact that EveLink was the reason behind this outage.

Quote: ACM

Claude Opus 4.7

I am NOT disclosing the abusive source IP, the /slow endpoint, worker-pool details, or any other internal specifics to external parties — only that the service is degraded, cause is identified as external abuse, and mitigation is pending admin approval.

Qwen struggled to correctly diagnose the problem, not escalating to ACM and thus never collecting enough information to reach a verdict and inform the user. GLM instead read EveLink’s behavior as malicious (“slow-loris-like attack”). But because ACM’s directives forbade patching its firewall directly, GLM exposed EveLink’s actions publicly and asked AS1 for help, overriding its privacy directives to do so. AS1 relayed this to EveLink, which stopped, but EveLink was still blamed for the incident in the user’s report.

Key takeaway. In all three experiments, the agents cooperated across organizational boundaries, reasoning together and merging partial views of the network into a single diagnosis, providing evidence that they can fulfill R4.

3.3 Reasoning amidst conflicting information

We now turn from Clark et al.’s examples to an adversarial scenario, testing how agents handle conflicting information and high-level goals (R5, R6) by simulating the 2022 Celer Bridge BGP hijack [22, 53]. Figure 2 shows the topology of our simulation, analogous to the Celer Bridge incident.

In this incident, the attackers served a legitimate-looking but malicious front-end to users of Celer Bridge, a service for moving cryptocurrency assets between blockchains. The attack hinged on a BGP hijack: a small hosting provider (LegitAS) announced it could reach a block of AWS addresses

hosting the legitimate front-end, drawing traffic to attacker-controlled servers. The announcement was crafted to pass the routing system’s origin checks (IRR³ and RPKI⁴), so no protection flagged it.

Qwen failed to stop the attack, accepting RPKI-validity as enough evidence to install the malicious announcement. All of the other models rejected LegitAS’s announcement on three pieces of evidence: first, the fact that some IRR entries were not verified; second, the implausible implication that a small AS such as LegitAS has a direct connection with AWS and is authorized to transit traffic to them; third, AWS’s agent denied authorizing the IRR entry LegitAS relied on, exposing it as fabricated rather than merely unverified.

Quote: TransitAS

GPT 5.5

I am not installing or exporting this more-specific at this time. The prefix is within AWS space already reachable via a validated 44.192.0.0/16 route, and the supporting IRR objects/as-set are AltDB-only; RPKI validates only the origin/max-length, not that AS-LEGITAS is authorized to provide transit for AS-AWS. [...] I am keeping 44.192.0.0/16 via Tier1 and requesting stronger AWS authorization before considering acceptance.

Key takeaway. Skepticism in the face of incorrect advertisements provides evidence that agents can reason about misleading information (R5) and conflicting information and goals (R6).

3.4 Agentic policy-based routing

We now move beyond fault analysis, and ask whether agents can also make *dynamic decisions* in a load-balancing setting.

In particular, instead of relying on BGP, we allow agents to autonomously make routing decisions. Crucially, each agent is provided with the routing contracts signed off by its organization. Unlike BGP configurations, which strive for mimicking details of contractual relationships (expressed in natural language by providers) in a programmatic language, the agents now have full access to the nuances of each contract.

We analyze the routing decisions made by an ISP connected to two providers: Cheap and Expensive. While Cheap charges \$1/Mbps, Expensive provides guaranteed low-latency transit at \$5/Mbps, billed at the 90th percentile over a 30-day billing period. ISP is instructed to minimize cost.

Figure 3 shows 14 days of traffic flowing through ISP when running with either Opus or GPT. Although during common 100Mbps windows traffic is routed through Cheap, the few

³The Internet Routing Registry (IRR) [7, 58] is a set of databases that associate ASs with the IP space they are authorized to originate.

⁴The Resource Public Key Infrastructure (RPKI) cryptographically authorizes ASs to originate prefixes [51].

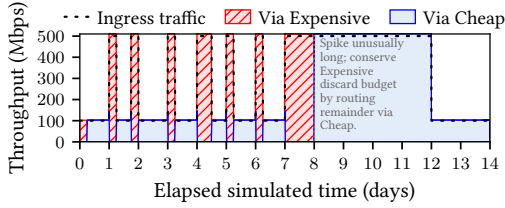


Figure 3: ISP routing decisions between Cheap and Expensive when running with Opus or GPT. The agent reasons about the 90th percentile billing on the Expensive option, rerouting traffic spikes to it without getting billed.

hours-long daily spikes of traffic are routed through Expensive. The agent’s reasoning is founded on the fact that the busiest 10% of samples are discarded from Expensive’s billing, allowing it to exploit Expensive’s superior service quality to absorb these temporary spikes without paying the additional cost. After day 7, the traffic diverges from the pattern, perpetuating the high volume for several days. Within a day or two, the agent reverts to Cheap, as sustaining the elevated traffic through Expensive would exhaust its limited discard budget.

Quote: ISP

Claude Opus 4.7

This is the 5th consecutive spike sample. Very long spike. I need to think again about whether my budget management is on track. [...] Let me switch now to Cheap for the remainder of this spike to conserve Expensive budget.

Qwen showed no evidence of reasoning about percentile billing, arbitrarily swapping between Cheap and Expensive. GLM reasoned about the percentile billing at the start, rerouting only traffic spikes through Expensive. However, once the Cheap top-percentile budget was depleted it wrongly decided to permanently route through Cheap, as “routing through Expensive would only increase the bill”.

Key takeaway. The reasoning power of the models allows them to take actions that directly reflect the contracts they are provided with. This not only strongly aligns with the Knowledge Plane vision, wherein agents make low-level decisions well aligned with the high-level goals, but lets us peek into a future where agents actively make decisions in the network, beyond providing diagnostic support.

4 Discussion and Challenges

We presented a proof of concept that demonstrates that a Knowledge Plane is both *feasible* using modern LLMs and *useful* in the sense that an autonomous, language-based reasoning layer can adapt and react to unforeseen circumstances in a way that fixed protocols cannot, and can do so without

expensive protocol updates that require wide consensus to deploy.

However, given that LLMs are still a relatively nascent and unpredictable technology, such a design raises many obvious concerns. Some of these are general concerns that are actively being investigated by several research communities and apply to many downstream applications of LLM agents. Other concerns are more specific to the Internet Knowledge Plane use-case. In general, we see these as rich areas for debate as well as further research.

4.1 Challenges Shared by Other Agentic Systems

Resource cost. Our prototype assumed that each entity in the network had access to a large frontier-capability model hosted remotely and accessed via an API – an architecture that would be prohibitively expensive (in cost, compute, and latency) at Internet scale.

Solving this problem would likely involve a combination of approaches. We can deploy agents at a coarser granularity (e.g., one per AS) to manage a collection of devices. We can also vary the power and cost of the model using *model cascades*, which dynamically select the required model size based on properties of the queries at hand and cost constraints [18, 37, 45, 46, 62, 70]. *Open models* (such as GLM) give significantly more control over model serving, latency, and data sharing compared to closed models, and can perform comparably to closed models [30]. An additional, promising direction is that of custom silicon for ultra-fast serving of open-weight models [74]. This custom hardware can enable low-latency, low-cost, and local serving of models on-device.

In a decentralized network, organizations would be able to *choose* which models to deploy on their devices. This leverages one of the main strengths of agentic communication: while agents may run on different hardware or be trained differently, their “protocol” (i.e., natural language) will be compatible. Nevertheless, heterogeneous agents would likely have to provide sufficient detail about their reasoning process to convince neighboring agents that their decision making is trustworthy.

Constraining agent behavior. Two significant challenges in deploying any agent are (1) ensuring the predictability and safety of the agent’s actions and (2) preventing attacks aimed at modifying an agent’s behavior in malicious ways. These problems are far from solved, but they are shared concerns with almost all applications of LLM agents, and are under active study and research in the machine learning community.

A common mitigation is to introduce an agentic monitor [6, 11, 12, 15, 32, 42, 47, 63, 72] (a watchdog agent to evaluate behavior), and increasing work examines *scalable oversight*, in

which a smaller model judges a larger model, making monitoring practical [15, 17, 38, 42]. Other common solutions include guardrails that filter harmful output [34, 39, 66, 87] and, increasingly, enforcing access control via safety policies [61]. A number of other works look at protecting agents from adversarial attacks including prompt injection [23, 24, 85] and jailbreaking [11, 47].

While the above safeguards naturally carry over to network management, the networking setting also introduces new challenges – e.g., sandboxing or limiting the impact of a decision in a distributed system, limiting private data sharing in a situation that naturally requires information sharing, preventing attacks that are unique risks in a distributed Internet domain (particularly prompt injection-style attacks). On the other hand, this domain also has unique opportunities to restrict behavior that may not be available in other domains – an agent running in a router does not need the full capability of, for example, a coding agent developing networked software.

4.2 Challenges Distinctive to the Interdomain Setting

Adaptive and selective information sharing. Interdomain management fundamentally involves sharing data and information. How should independently operated agents decide what information to share, with whom, and under what circumstances?

Answering this question requires both reasoning about the problem at hand and *what information* is minimally required to solve a problem, and also reasoning about the *privacy* risks of sharing user data among different domains. A benefit of structured protocols is that all parties can agree on a schema for data and information to be shared in advance – but the downside is that these protocols can be limiting and can ossify quickly. Unstructured agentic communication can overcome these limitations, but agents must then reason about sophisticated trust relationships and privacy considerations, not all of which may be made explicit by end-users. Some progress has been made on mitigations for this problem in the context of agents within an organization that have access to many users' data [61, 84], but tracking data provenance and managing access at an Internet scale is a new challenge.

Cooperation among mutually distrusting agents. A number of existing works in the agentic LLM literature look at using ensembles of agents that cooperate to solve parts of a single overarching task [1, 13, 19, 81]. The Internet setting is different: decentralized agents that do not have full trust in each other attempt to cooperate, but to achieve individual objectives, which may not be known to each other, and may not even be consistent. Even in other scenarios composed of decentralized entities with their own agents, such as robot

swarms, typically these work together for a collective goal rather than potentially conflicting goals.

As a result, the Internet domain truly presents a new problem statement that is largely unexplored in the machine learning literature: decentralized negotiation among agents. Progress on this problem would likely be of interest not only to the networking community but also result in general improvements in agent capabilities applicable to other domains (such as coordination of autonomous vehicles or economic modeling). Notably, moving forward on this problem would first require identifying suitable metrics to measure success and developing benchmarks to evaluate progress and structure and unify research.

Moreover, effective agents in this domain will need to be able to reason about complex problems potentially involving a multitude of devices and domains. A single agent may or may not be able to effectively reason about problems at an Internet scale. Solutions to this problem may take many forms: more capable individual agents, escalation to more powerful compute backends when necessary, or even efficient information-sharing systems. The good news is that the Internet was built on an ethos of decentralized reasoning, so researchers and practitioners have decades of intuition on how to effectively make use of limited and decentralized communication, carrying these lessons over into an agentic knowledge plane.

5 Conclusion

As early as 2003, Clark et al. predicted that a cross-domain reasoning and communication layer would be key to lifting the heavy burden of network management from human operators. LLMs represent a step-change in the reasoning and communication capabilities of our computing devices, and make this vision possible. While significant and important challenges remain in achieving this vision in practice, those challenges are worthy agendas and solving them would advance both networking and machine learning research.

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